

### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### **Device Features**

- AEC-Q100 Grade 2 Qualified
- 7-bit Serial & Parallel Interface
- 31.75dB Control Range 0.25dB step
- Support addressable Function (Addr0-Addr7)
- Glitch-safe attenuation state transitions
- 2.7V to 5.5V supply
- Low Current Consumption 200μA typical
- 1.17V to 3.6V control logic
- Excellent Attenuation Accuracy

 $\pm$ (0.15 + 1.5% of attenuation state) @ 1.9GHz

 $\pm$ (0.25 + 3.5% of attenuation state) @ 3.5GHz

 $\pm$ (0.25 + 7.0% of attenuation state) @ 7.2GHz

- Low Insertion Loss
  - 1.0 dB @ 1.9GHz
  - 1.3 dB @ 3.5GHz
  - 2.8 dB @ 7.2GHz
- Ultra linearity IIP3 > +68dBm @ 3.5GHz, ATT=0dB
- Input 0.1dB Compression (P0.1dB) 30dBm @ 3.5GHz, ATT=0dB
- Programming modes
  - Direct parallel
  - Latched parallel
  - Serial Addressable
- -40°C to +105°C operating temperature
- ESD rating : Class1C (1kV HBM)
- Lead-free/RoHS2-compliant 32-lead 5mm x 5mm x 0.9mm QFN SMT package
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32-lead 5mm x 5 mm x 0.9mm QFN

Figure 1. Package Type

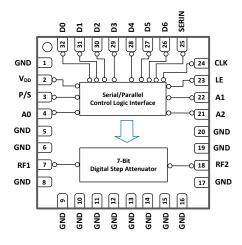


Figure 2. Functional Block Diagram

### **Product Description**

The BDA4710V/BDA4710VT is a broadband, Highly accurate  $50\Omega$  digital step attenuator model which provides adjustable attenuation from 0 to 31.75 dB in 0.25 dB steps. The control interface supports a 7-bit serial interface with 3-bit addressable function and latched parallel interface

BDA4710V/BDA4710VT supports a broad operating frequency range from 1MHz to 9.0 GHz. BDA4710V/BDA4710VT is offering the High linearity, low power consumption, high attenuation accuracy and low insertion loss, typically less than 3.0dB up to 8.5GHz.

The device features a safe state transitions with no negative/positive Glitch technology optimized for excellent step accuracy.

Basically the RF input and output are internally matched to 50  $\Omega$  and do not require any external matching components. In some cases to optimize Return loss for above 4 - 8.5GHz, Shunt capacitor can be added near RF1 and RF2 respectively. The design is bi-directional; Therefore, the RF input and output are interchangeable.

The BDA4710V/BDA4710VT does not require blocking capacitors. If DC is presented at the RF port, add a blocking capacitor. This is packaged in a RoHS2-compliant with QFN surface mount package.

The BDA4710V/BDA4710VT is AEC-Q100 Grade 2 qualified.

### **Application**

- Automotive
- Vehicle to Everything(V2X)
- Telematics / Infotainment / ADAS
- WLAN 802.11 a/n/ac/ax
- Remote Keyless Entry
- GPS/Navigation
- Wireless control systems

### **Ordering Information**

Part Number	Descriptions
BDA4710V	Mass Test in RT(+25°C)
BDA4710VT	Mass Test in LT(-40C°) / RT(+25°C) / HT(+105°C)
BDA4710V-EVB BDA4710VT-EVB	BDA4710V/BDA4710VT Evaluation Board
BDA4710V-EVK	BDA4710V/BDA4710VT Evaluation Board Kit
BDA4710VT-EVK	( Evaluation Board + Control Board )

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### **Table 1. Electrical Specifications**

Specifications are performance on the BeRex EVKit at VDD=3.3V, 25°C, 50Ω system. Performance were measured based on Typical application circuits Table 13. (See the Page 9)

	Parameter	Condition	Frequency	Min	Тур	Max	Unit
Fr	equency Range			1		8000	MHz
	tenuation range	0.25dB step			0 - 31.75		dB
			1MHz - 1GHz		0.8		dB
			1 - 2GHz		1.0		dB
1	nsertion Loss <sup>1</sup>	ATT = 0dB	2 - 4GHz		1.5		dB
			4 - 6GHz		2.6		dB
			6 - 8GHz		2.9		dB
		0.25dB Step					
			1MHz - 2GHz				
			2 - 3GHz			±(0.15 + 2.5% of	
		0-31.75dB	3 - 5GHz			±(0.25 + 3.5% of	dB
		4 10 5:	5 - 6GHz			attenuation state)	
At	ttenuation Error	1dB Step	1			+(0.15 + 1.5% of	1
			1MHz - 2GHz			attenuation state)	
			2 - 3GHz			±(0.15 + 2.5% of attenuation state)	
		0-31.0dB	3 - 5GHz			±(0.25 + 3.5% of attenuation state)	dB
			5 - 6GHz			±(0.25 + 5.0% of	
			6 - 8GHz			±(0.25 + 7.0% of	
			1 - 4GHz		20	attenuation state)	
In	put Return Loss	ATT = 0dB	4 -8GHz		10	#(0.15 + 1.5% of attenuation state)  ±(0.15 + 2.5% of attenuation state)  ±(0.15 + 2.5% of attenuation state)  ±(0.25 + 3.5% of attenuation state)  ±(0.25 + 5.0% of attenuation state)  ±(0.15 + 1.5% of attenuation state)  ±(0.15 + 2.5% of attenuation state)  ±(0.25 + 3.5% of attenuation state)  ±(0.25 + 3.5% of attenuation state)  ±(0.25 + 5.0% of attenuation state)	
			1 - 4GHz		20		dB
Ou	tput Return Loss	ATT = 0dB	4 - 8GHz		10		
			1GHz		6		
			2GHz		12		
			3GHz		19		
Rela	ative Phase Error	All States	4GHz		27		degree
			5GHz		35		
			6GHz		43		
	Input 0.1dB Compression point	ATT = 0dB	3.5GHz		30		dBm
	compression point	Pin = +18dBm/tone, $\triangle f$ = 20MHz	2.5GHz		63		
		ATT = 0.0dB	3.5GHz		68		
		RF Input = RF1 Port	4.5GHz		59		
			7.25GHz		52		
		Pin = +18dBm/tone, $\triangle f$ = 20MHz	2.5GHz		59		
		ATT = 31.75dB	3.5GHz		58		
Input		RF Input = RF1 Port	4.5GHz		54		
Linearity	Immust ID2		7.25GHz		51		dD.m.
	Input IP3	Pin = +18dBm/tone, $\triangle f$ = 20MHz	2.5GHz		64		dBm
		ATT = 0.0dB	3.5GHz		60		]
		RF Input = RF2 Port	4.5GHz		58		]
			7.25GHz		49		
		Pin = +18dBm/tone, $\triangle f$ = 20MHz	2.5GHz		58		
		ATT = 31.75dB	3.5GHz		57		
		RF Input = RF2 Port	4.5GHz		56		
			7.25GHz		42		

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### 7-bit Digital Step Attenuator with Addressable Function for Automotive

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### Table 1. Electrical Specifications (Cont.)

Parameter Condition		Frequency	Min	Тур	Max	Unit
RF Rising / Falling Time	2GHz		121		ns	
Switching time	50% CTRL to 90% or 10% RF	2GHz		224		ns
Settling time	50% CTRL to Max or Min Attenuation to settle within 0.05 dB of final value	2GHz		500		ns
Attenuation Transient (envelope) <sup>2</sup>	Positive glitch, Any ATT step	3.5GHz		0.3		dB
Maximum Spurious level	Measured at RF1 and RF2 port	1 - 5MHz		-142		dBm/10Hz
	ivieasureu at Kri anu Krz port	>5MHz <sup>3</sup>		< -145		ubili/10HZ

- 1. The Evaluation board Kit insertion loss (PCB & RF Connector) is de-embedded.
- 2. Attenuation Transient is glitch level due to attenuation transitions
- 3. No spurious signals were detected above 5MHz.

### Table 2. Electrical Specifications<sup>1</sup> (Optimized Return Loss Application )

Specifications are performance on the BeRex EVKit at VDD=3.3V, 25°C, 50  $\Omega$  system. Performance were measured based on Optimized Return Loss Application Circuits Table 14. ( See the Page 16 )

Parameter	Condition	Frequency	Min	Тур	Max	Unit
Frequency Range			1		9000	MHz
Attenuation range	0.25dB step			0 - 31.75		dB
		1MHz - 1GHz		0.7		dB
		1 - 2GHz		1.0		dB
		2 - 3GHz		1.1		dB
Insertion Loss <sup>2</sup>	ATT = 0dB	3 - 4GHz		1.3		dB
		4 - 6GHz		1.8		dB
		6 - 8GHz		2.6		dB
		8– 9GHz		3.8		dB
		1MHz - 2GHz			$\pm$ (0.15 + 1.5% of attenuation state)	dB
		2 - 3GHz			$\pm$ (0.15 + 2.5% of attenuation state)	dB
Attenuation Error	0-31.75dB / 0.25dB Step	3 - 4GHz			$\pm$ (0.25 +3.5% of attenuation state)	dB
		4 - 6GHz			$\pm$ (0.25 +5.0% of attenuation state)	dB
		6 - 9GHz			$\pm$ (0.25 +5.0% of attenuation state) $\pm$ (0.35 +7.0% of attenuation state)	dB
		1 - 4GHz		18		
Input Return Loss	ATT = 0dB	4 - 6GHz		15		dB
		6 - 9GHz		20		
		1 - 4GHz		19		
<b>Output Return Loss</b>	ATT = OdB	4 - 6GHz		16		dB
		6 - 9GHz		17		
		1GHz		6		
		2GHz		11		
		3GHz		18		
		4GHz		26		
Relative Phase Error	All states	5GHz		34		degree
		6GHz		43		
		7GHz		52		
		8GHz		65		
		9GHz		76		

<sup>1.</sup> In order to improve Return loss above 4GHz, shunt capacitor 0.1pF was added to each RF1 & RF2. (See Optimized Return loss application circuits Table 14 on page 16)

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<sup>2.</sup> The Evaluation board Kit insertion loss (PCB & RF Connector) is de-embedded.



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**Table 3. Recommended Operating Condition** 

Parameter	Parameter		Condition	Min	Тур	Max	Unit
Supply Voltages	Supply Voltages			2.7		5.5	V
Supply Current	Supply Current				200	350	μΑ
Digital Control Input	High	V <sub>CTLH</sub> V	V <sub>CTLH</sub> V <sub>DD</sub> =3.3V or 5V	1.17		3.6	V
Digital control input	Low	V <sub>CTLL</sub>	V <sub>DD</sub> =3.3V or 5V	-0.3		0.6	٧
Operating Temperature	Operating Temperature Range		Exposed Paddle	-40		105	°C
RF Max Input Powe	RF Max Input Power		RF1 or RF2, CW (> 50MHz)			24	dBm
Impedance	Impedance		Single ended	·	50		Ω

Specifications are not guaranteed over all recommended operating conditions.

**Table 4. Absolute Maximum Ratings** 

Pa	rameter	Symbol	Min	Тур	Max	Unit
Supp	ly Voltage	$V_{DD}$	-0.3		5.5	V
Digital Input Voltage		$V_{CTL}$	-0.3		3.6	٧
Maximum Input Power		P <sub>IN_CWMAX</sub>			31	dBm
Temperature	Storage	T <sub>ST</sub>	-65		150	$^{\circ}$ C
remperature	Reflow	T <sub>R</sub>			260	$^{\circ}$ C
ESD Sensitivity	HBM <sup>1</sup>	ESD <sub>HBM</sub>			±1000 (Class 1C)	V
LSD Sensitivity	CDM <sup>2</sup>	ESD <sub>CDM</sub>			±1000 (Class C3)	V

Operation of this device above any of these parameters may result in permanent damage.

**Table 5. Package Thermal Characteristics** 

Parameter	Symbol	Value	Unit
Junction to Ambient Thermal Resistance	$\theta_{JA}$	30.1	°C/W

<sup>1.</sup> HBM : Human Body Model (AEC-Q100-002)

<sup>2.</sup> CDM: Charged Device Model (AEC-Q100-011)

8 GND CLK 24  $V_{\text{DD}}$ (23 LE P/S 22 **A1 A2** Α0 **Exposed Ground Pad** GND **GND** GND **GND** RF1 18 RF2 8 GND GND 

Figure 3. Pin Configuration (Top View)

Table 6. Pin Description

Pin	Pin name	Description
1, 5, 6, 8-17, 19,20	GND	Ground, These pins must be connected to ground
2	VDD	Power Supply (nominal 3.3V)
3	P/S	Parallel/Serial Mode Select. For parallel mode operation, set this pin to LOW. For serial mode operation, set this pin to HIGH.
4	A0	Address bit A0 connection.
7	RF1 <sup>1</sup>	RF1 port (Attenuator RF Input)
,	RF1	This pin can also be used as an output because the design is bidirectional. RF1 is $$ dc-coupled and matched to 50 $$ $\Omega$
18	RF2 <sup>1</sup>	RF2 port (Attenuator RF Output.)
18	KF2	This pin can also be used as an input because the design is bidirectional. RF2 is dc-coupled and matched to $50  \Omega$ .
21	A2	Address bit A2 connection.
22	A1	Address bit A1 connection.
23	LE	Latch Enable input
24	CLK	Serial interface clock input
25	SERIN	Serial interface data input
26	D6 <sup>2</sup>	Parallel Control Voltage Inputs, Attenuation control bit 16dB
27	D5 <sup>2</sup>	Parallel Control Voltage Inputs, Attenuation control bit 8dB
28	D4 <sup>2</sup>	Parallel Control Voltage Inputs, Attenuation control bit 4dB
29	D3 <sup>2</sup>	Parallel Control Voltage Inputs, Attenuation control bit 2dB
30	D2 <sup>2</sup>	Parallel Control Voltage Inputs, Attenuation control bit 1dB
31	D1 <sup>2</sup>	Parallel Control Voltage Inputs, Attenuation control bit 0.5dB
32	DO <sup>2</sup>	Parallel Control Voltage Inputs, Attenuation control bit 0.25dB
Pad	GND	Exposed pad: The exposed pad must be connected to ground for proper operation

<sup>1.</sup> RF pins 7 and 18 must be at 0V DC. The RF pins do not require DC blocking capacitors for proper Operation if the 0V DC requirement is met.

2. It is recommended to ground the D0  $^{\sim}$  D6 in serial mode.

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### 7-bit Digital Step Attenuator with Addressable Function for Automotive

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### **Programming Options**

BDA4710V/BDA4710VT can be programmed using either the parallel or serial interface, which is selectable via P/S pin(Pin3). Serial mode is selected by pulling it to a voltage logic HIGH and parallel mode is selected by setting P/S to logic LOW

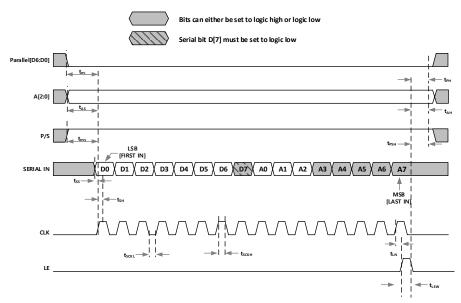
### Serial Control Mode

The serial interface is a 16-bit shift register to shift in the data LSB (D0) first. When serial programming is used, It is recommended all the parallel control input pins (26, 27, 28, 29, 30, 31, 32) are grounded. It is controlled by three CMOS-compatible signals: SERIN, Clock, and Latch Enable (LE).

Table 7. Truth Table for Serial Control Word

	Digital Control Input												
D7 (MSB)	D6	D5	D4	D3	D2	D1	D0 (LSB)	state (dB)					
LOW	LOW	LOW	LOW	LOW	LOW	LOW	LOW	0 (RL)					
LOW	LOW	LOW	LOW	LOW	LOW	LOW	HIGH	0.25					
LOW	LOW	LOW	LOW	LOW	LOW	HIGH	LOW	0.5					
LOW	LOW	LOW	LOW	LOW	HIGH	LOW	LOW	1.0					
LOW	LOW	LOW	LOW	HIGH	LOW	LOW	LOW	2.0					
LOW	LOW	LOW	HIGH	LOW	LOW	LOW	LOW	4.0					
LOW	LOW	HIGH	LOW	LOW	LOW	LOW	LOW	8.0					
LOW	HIGH	LOW	LOW	LOW	LOW	LOW	LOW	16.0					
LOW	HIGH	HIGH	HIGH	HIGH	HIGH	HIGH	HIGH	31.75					

Figure 4. Serial Mode Timing Diagram



BDA4710V/BDA4710VT Serial mode is selected by pulling it to logic HIGH. The serial interface is a 16-bit shift register made up of two words. The first 8-bit word is the Attenuation word, which controls the DSA state. The second word is the address word, which uses only 3 of 8-bits that must match the hard wired A0-A2 programming in order to change the DSA state. If no external connections are made to A0-A2 then internally they will default to 000 due to internal pull down resistors. If these 3 external preset address bits are not matched with the SPI loaded address bits then the current attenuator state will remain unchanged. This allows up to 8 serial-controlled devices to be used on a single board, which share a common SERIN, CLK and LE.

When serial programming is used, all the parallel control input pins 26-32 can be left open or grounded.

**Table 8. Serial Interface Timing Specifications** 

Symbol	Parameter	Min	Тур	Max	Unit
f <sub>CLK</sub>	Serial data clock frequency			10	MHz
t <sub>PS</sub>	Parallel data setup time	100			ns
t <sub>PH</sub>	Parallel data hold time	100			ns
t <sub>AS</sub>	Address setup time	100			ns
t <sub>AH</sub>	Address hold time	100			ns
t <sub>PSS</sub>	Parallel/Serial setup time	100			ns
t <sub>PSH</sub>	Parallel/Serial hold time	100			ns
t <sub>ss</sub>	Serial Data setup time	10			ns
$t_{SH}$	Serial Data hold time	10			ns
t <sub>SCKH</sub>	Serial clock high time	30			ns
t <sub>SCKL</sub>	Serial clock low time	30			ns
t <sub>LN</sub>	LE setup time	10			ns
t <sub>LEW</sub>	Minimum LE pulse width	30			ns

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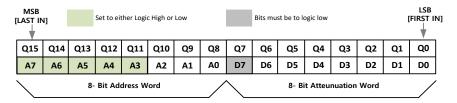
1MHz - 9000MHz

### Serial Register Map

The BDA4710V/BDA4710VT can be programmed via the serial control on the rising edge of Latch Enable (LE) which loads the last 8-bits attenuation word and 8-bits address word in the SHIFT Register. Data is clocked in LSB(D0) first.

The shift register must be loaded while LE is kept LOW to prevent changing the attenuation value during data is inputted.

Figure 5. Serial Register Map



The serial register consist of 16 bits as shown in Figure 5. First 8 bits from LSB are Attenuation word, 8 bits after that are Address word. The Attenuation word is DSA attenuation control bit and the Address word is static logical bit determined by A0, A1 and A2 digital inputs. The attenuation word is derived directly from the value of the attenuation state. To find the attenuation word, multiply the value of the state by four because of 0.25dB step up to 31.75dB (total 127 Attenuation state), then convert to binary.

For example, to program attenuation 15.75dB state of Addr[5] BDA4710V/BDA4710VT:

Attenuation State Address state

4 x 15.75 = 63 Digital input of A2, A1, A0 pin = 101

63 -> 00111111 A7 - A0: xxxxx101

Serial Input: xxxxx10100111111

х	х	х	х	х	1	0	1	0	0	1	1	1	1	1	1
Α7	Α6	A5	A4	А3	A2	Α1	Α0	D7	D6	D5	D4	D3	D2	D1	D0

Table 9. Truth Table for Address Control Word

		Addres							
A7 (MSB)	A6	A5	A4	А3	A2	A1	A0 (LSB)	Address Setting	Addr No.
Х	Х	Х	Х	Х	LOW	LOW	LOW	000	Addr[0]
Χ	Х	Х	Х	Х	LOW	LOW	HIGH	001	Addr[1]
Χ	Х	Х	Х	Х	LOW	HIGH	LOW	010	Addr[2]
Х	Х	Х	Х	Х	LOW	HIGH	HIGH	011	Addr[3]
Χ	Х	Х	Х	Х	HIGH	LOW	LOW	100	Addr[4]
Χ	Х	Х	Х	Х	HIGH	LOW	HIGH	101	Addr[5]
Χ	Х	Х	Х	Х	HIGH	HIGH	LOW	110	Addr[6]
Х	Χ	Х	Х	Х	HIGH	HIGH	HIGH	111	Addr[7]

Table 10. Mode Selection

P/S	Control Mode
LOW	Parallel
HIGH	Serial Addressable

### **Power-UP states Settings**

The BDA4710V/BDA4710VT will always initialize to the maximum attenuation setting (31.75 dB) on power-up for both the Serial and Latched Parallel modes of operation and will remain in this setting until the user latches in the next programming word.

In Direct Parallel mode, the DSA can be preset to any state within the 31.75 dB range by pre-setting the Parallel control pins prior to power-up. In this mode, there is a 400  $\mu$ s delay between the time the DSA is powered-up to the time the desired state is set.

Figure 6. Default Attenuation Word for Power-up state

0	1	1	1	1	1	1	1
D7	D6	D5	D4	D3	D2	D1	D0
$\overline{\ \ }$		8- Bi	t Atteu	nuation	Word		_/

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### **Programming Options**

### **Parallel Control Mode**

The parallel control interface has seven digital control input lines (D6 to D0) to set the attenuation value. D6 is the most significant bit (MSB) that selects the 16 dB attenuator stage, and D0 is the least significant bit (LSB) that selects the 0.25 dB attenuator stage (see Figure 7).

### **Direct Parallel Mode**

For direct parallel mode, The LE pin must be kept HIGH. The attenuation state is changed by the control voltage inputs (D0 to D6) directly. This mode is ideal for manual control of the attenuator. In this mode the device will immediately react to any voltage changes to the parallel control pins [pins 26, 27, 28, 29, 30, 31, 32]. Use direct parallel mode for the fastest settling time.

#### **Latched Parallel Mode**

The LE pin must be kept LOW when changing the control voltage inputs (D0 to D6) to set the attenuation state. When the desired state is set, LE must be toggled HIGH to transfer the 7-bit data to the bypass switches of the attenuator array, and then toggled LOW to latch the change into the device until the next desired attenuation change (see Figure 7 and Table 11).

- Set P/S is logic LOW.
- Set LE to logic LOW.
- Adjust pins [26, 27, 28, 29, 30, 31, 32] to the desired attenuation setting. (Note the device will not react to these pins while LE is a logic LOW).
- Pull LE to a logic HIGH. The device will then transition to the attenuation settings reflected by pins D6 - D0.
- If LE is pulled to a logic LOW then the attenuator will not change state.

Latched Parallel Mode implies a default state for when the device is first powered up with P/S pin set for logic LOW and LE logic LOW. In this case the default setting is <u>Maximum attenuation</u>.

### **Switching Feature Description**

### Glitch-Safe Attenuation State Transient

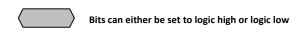
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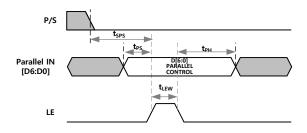
The BDA4710V/BDA4710VT is the latest product applied *Glitch-Safe* technology with less than 1dB ringing (pos/neg) across the attenuation range when changing attenuation states. This technology protects Amplifiers or ADC during transitions between attenuation states. (see Figure 40,41).

Table 11. Truth Table for the Parallel Control Word

D6	D5	D4	D3	D2	D1	D0	P/S	LE	Attenuation State(dB)
LOW	LOW	HIGH	0 (RL)						
LOW	LOW	LOW	LOW	LOW	LOW	HIGH	LOW	HIGH	0.25
LOW	LOW	LOW	LOW	LOW	HIGH	LOW	LOW	HIGH	0.5
LOW	LOW	LOW	LOW	HIGH	LOW	LOW	LOW	HIGH	1.0
LOW	LOW	LOW	HIGH	LOW	LOW	LOW	LOW	HIGH	2.0
LOW	LOW	HIGH	LOW	LOW	LOW	LOW	LOW	HIGH	4.0
LOW	HIGH	LOW	LOW	LOW	LOW	LOW	LOW	HIGH	8.0
HIGH	LOW	LOW	LOW	LOW	LOW	LOW	LOW	HIGH	16.0
HIGH	LOW	HIGH	31.75						

Figure 7. Latched Parallel Mode Timing Diagram





**Table 12. Parallel Interface Timing Specifications** 

Symbol	Parameter	Min	Тур	Max	Unit
t <sub>SPS</sub>	Serial to Parallel Mode Setup Time	100			ns
t <sub>LEW</sub>	Minimum LE pulse width	10			ns
t <sub>PH</sub>	Data hold time from LE	10			ns
t <sub>PS</sub>	Data setup time to LE	10			ns

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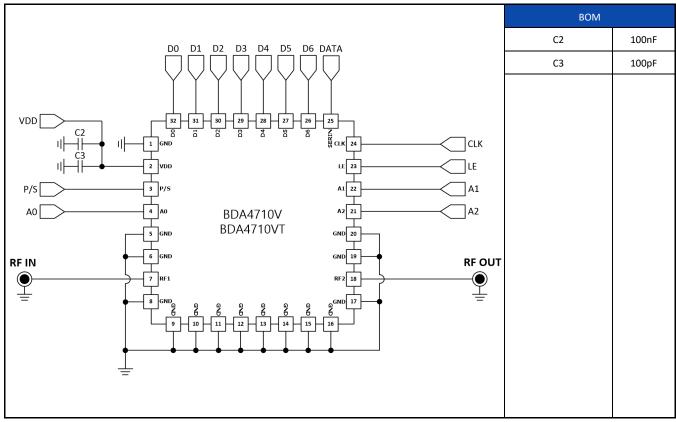
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### Typical RF Performance Plot - BDA4710V/BDA4710VT EVK - PCB (Typical Application Circuits)

Typical Performance Data @ 25°C and V<sub>DD</sub> = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

**Table 13. Typical Application Circuits** 



1. See the page 21 the Evaluation Board Circuits for the detailed application circuit information.



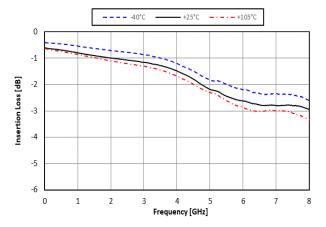
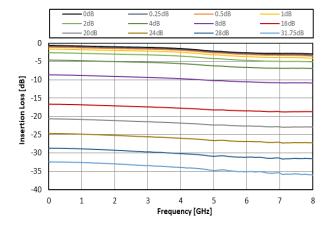


Figure 9. Insertion Loss vs ATT Setting



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### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### Typical RF Performance Plot - BDA4710V/BDA4710VT EVK - PCB (Typical Application Circuits)

Typical Performance Data @ 25°C and V<sub>DD</sub> = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 10. Input Return Loss vs ATT Setting

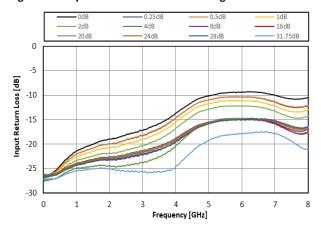


Figure 11. Output Return Loss vs ATT Setting

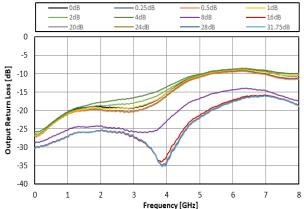


Figure 12. Input Return Loss vs Temp. @ ATT = 0dB

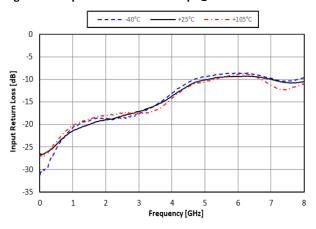


Figure 13. Output Return Loss vs Temp. @ ATT = 0dB

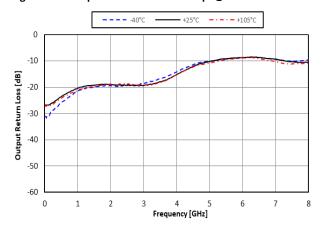


Figure 14. Relative Phase Error vs ATT Setting

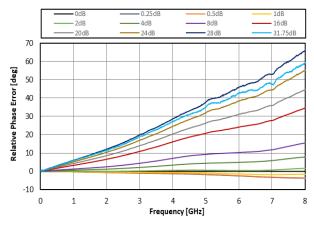
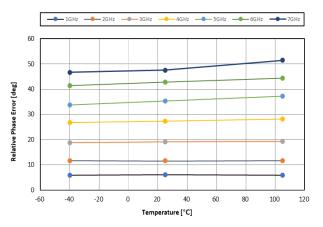


Figure 15. Relative Phase Error vs Frequency @ ATT = 31.5dB



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### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### Typical RF Performance Plot - BDA4710V/BDA4710VT EVK - PCB (Typical Application Circuits)

Typical Performance Data @ 25°C and V<sub>DD</sub> = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 16. ATT Error vs Temp. @ 900MHz

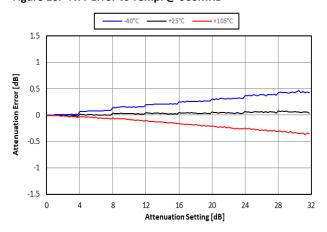


Figure 17. ATT Error vs Temp. @ 1800MHz

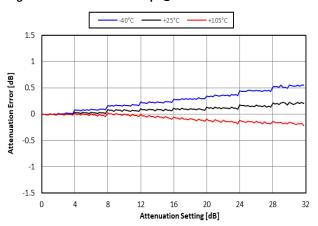


Figure 18. ATT Error vs Temp. @ 2200MHz

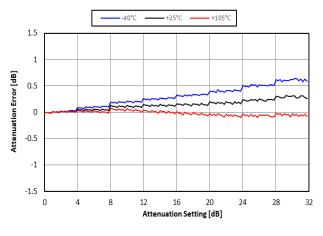


Figure 19. ATT Error vs Temp. @ 3500MHz

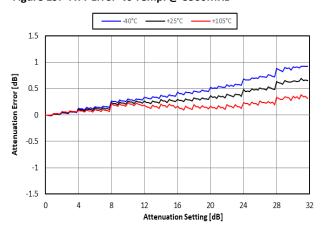


Figure 20. ATT Error vs Temp. @ 4600MHz

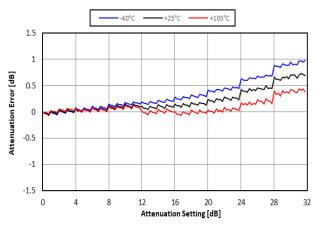
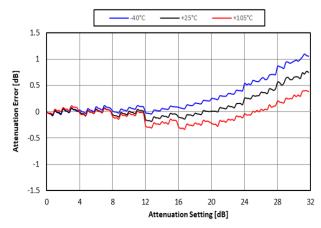


Figure 21. ATT Error vs Temp. @ 5800MHz



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### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### Typical RF Performance Plot - BDA4710V/BDA4710VT EVK - PCB (Typical Application Circuits)

Typical Performance Data @ 25°C and V<sub>DD</sub> = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 22. IIP3 vs Temp. @ 2500MHz

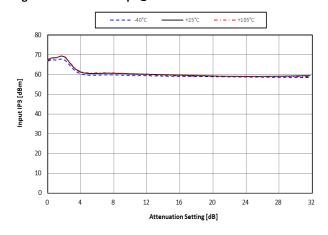


Figure 23. IIP3 vs Temp. @ 3500MHz

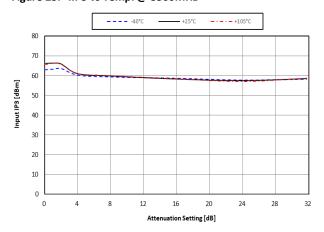


Figure 24. IIP3 vs Temp. @ 4500MHz

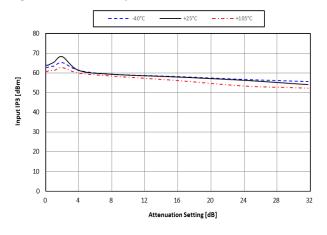


Figure 25. IIP3 vs Temp. @ 6400MHz

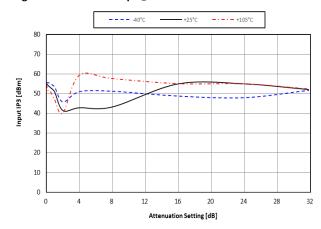


Figure 26. IIP3 vs Temp. @ 7250MHz

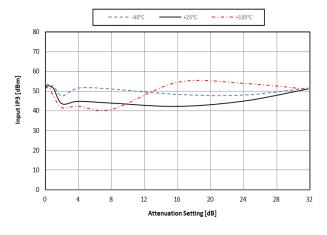
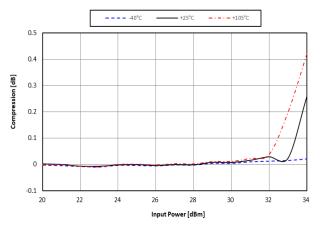


Figure 27. Input 0.1dB Compression vs Temp. @ 2500MHz



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### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### Typical RF Performance Plot - BDA4710V/BDA4710VT EVK - PCB (Typical Application Circuits)

Typical Performance Data @ 25°C and V<sub>DD</sub> = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 28. Input 0.1dB Compression vs Temp. @ 3500MHz

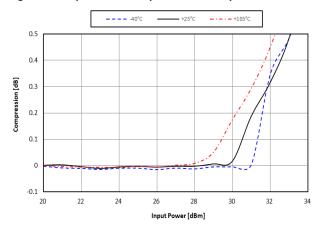


Figure 29. Input 0.1dB Compression vs Temp. @ 4500MHz

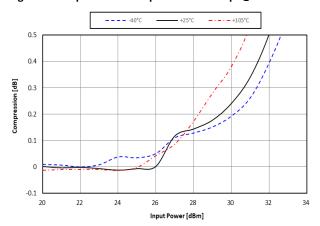


Figure 30. Input 0.1dB Compression vs Temp. @ 5500MHz

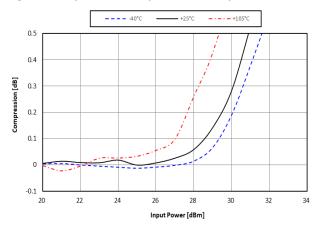


Figure 31. Input 0.1dB Compression vs Temp. @ 7250MHz

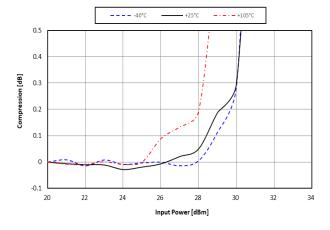


Figure 32. 0.25dB Step ATT vs Frequency

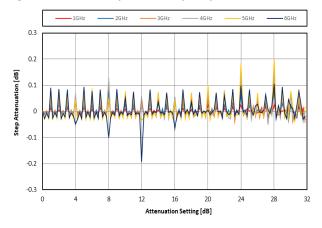
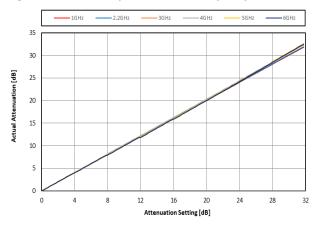


Figure 33. 0.25dB Step Actual ATT vs Frequency



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### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### Typical RF Performance Plot - BDA4710V/BDA4710VT EVK - PCB (Typical Application Circuits)

Typical Performance Data @ 25°C and V<sub>DD</sub> = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 34. 0.25dB Major State Bit Error vs ATT Setting

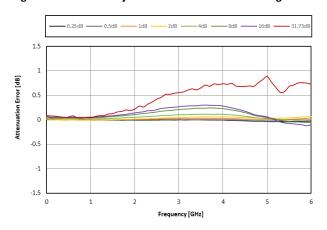


Figure 35. 0.25dB Step ATT Error vs Frequency

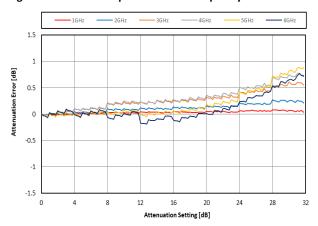


Figure 36. 1dB Step ATT vs Frequency

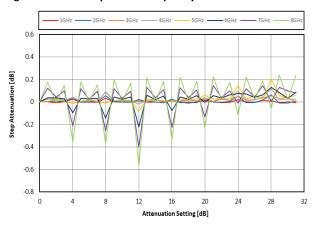


Figure 37. 1dB Step Actual ATT vs Frequency

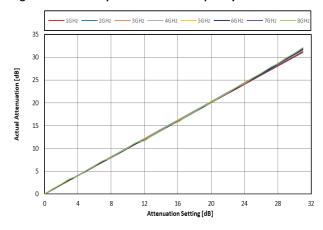


Figure 38. 1dB Major State Bit Error vs ATT Setting

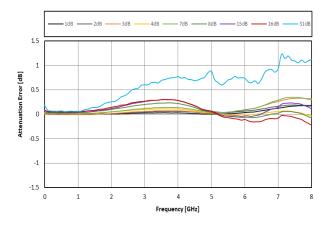
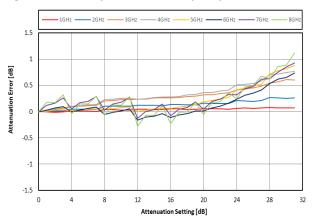


Figure 39. 1dB Step ATT Error vs Frequency



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### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### Typical RF Performance Plot - BDA4710V/BDA4710VT EVK - PCB (Typical Application Circuits)

Typical Performance Data @ 25°C and V<sub>DD</sub> = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 40. ATT Transient (15.75 to 16dB, Pin=18dBm)

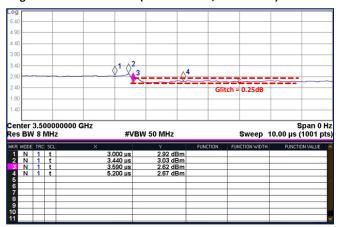
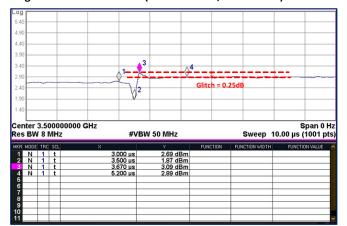


Figure 41. ATT Transient (16 to 15.75dB, Pin=18dBm)



Specifications and information are subject to change without notice.



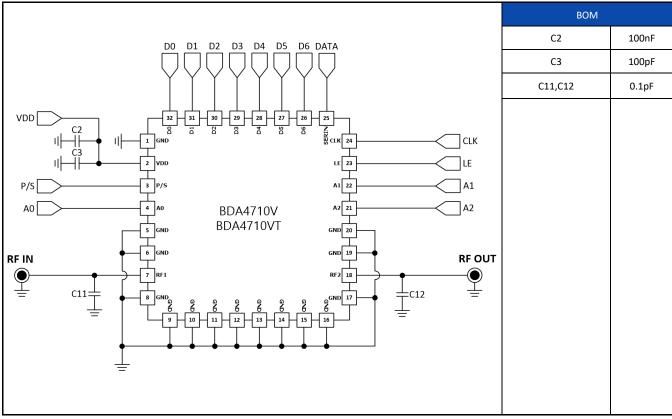
### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### Typical RF Performance Plot - BDA4710V/BDA4710VT EVK - PCB (Optimized Return Loss Application

Typical Performance Data @ 25°C and V<sub>DD</sub> = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Table 14. Optimized Return Loss Application Circuits for 4GHz - 8.5GHz



- 1. See the page 21 the Evaluation Board Circuits for the detailed application circuit information.
- 2. In order to optimized Return loss for above 4GHz, shunt capacitor 0.1pF was added near RF1 & RF2, respectively.

Figure 42. Insertion Loss vs Temp.

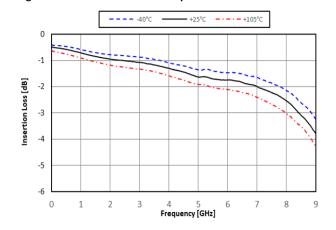
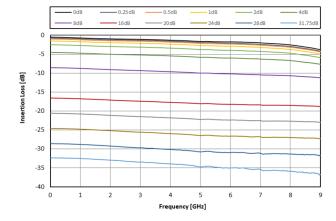


Figure 43. Insertion Loss vs ATT Setting



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### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### Typical RF Performance Plot - BDA4710V/BDA4710VT EVK - PCB ( Optimized Return Loss Application

Typical Performance Data @ 25°C and V<sub>DD</sub> = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 44. Input Return Loss vs ATT Setting

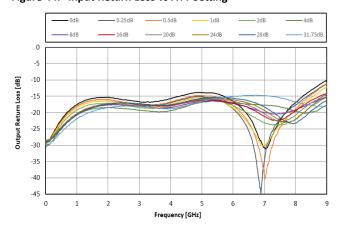


Figure 45. Output Return Loss vs ATT Setting

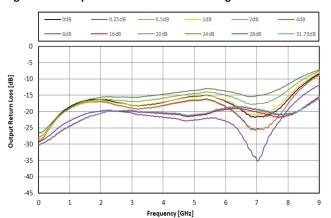


Figure 46. Input Return Loss vs Temp. @ ATT = 0dB

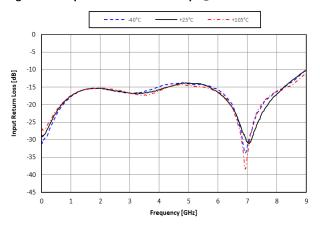


Figure 47. Output Return Loss vs Temp. @ ATT = 0dB

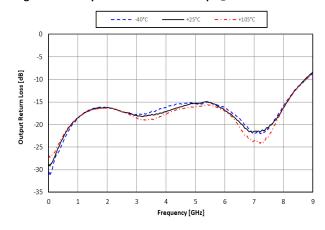


Figure 48. Relative Phase Error vs ATT Setting

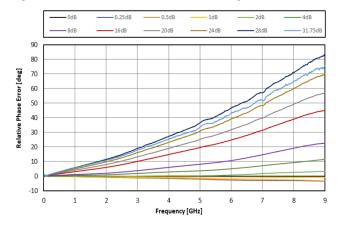
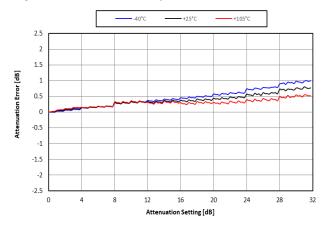


Figure 49. ATT Error vs Temp. @ 3500MHz



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### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### Typical RF Performance Plot - BDA4710V/BDA4710VT EVK - PCB (Optimized Return Loss Application

Typical Performance Data @ 25°C and V<sub>DD</sub> = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 50. ATT Error vs Temp. @ 4600MHz

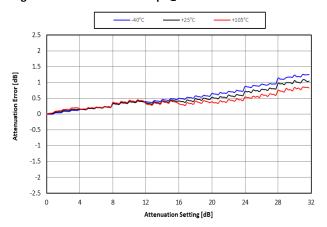


Figure 51. ATT Error vs Temp. @ 5800MHz

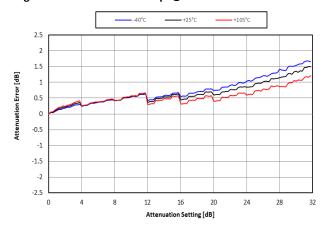


Figure 52. ATT Error vs Temp. @ 7200MHz

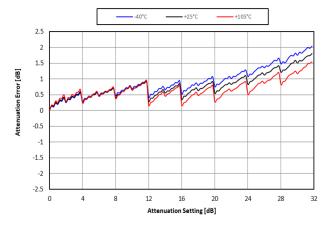


Figure 53. ATT Error vs Temp. @ 8500MHz

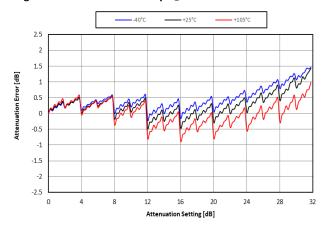


Figure 54. 0.25dB Step Actual ATT vs Frequency

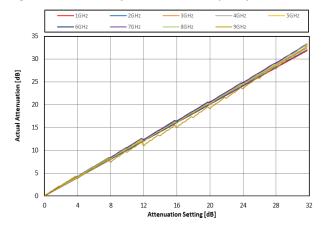
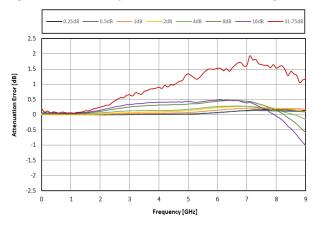


Figure 55. 0.25dB Major State Bit Error vs ATT Setting



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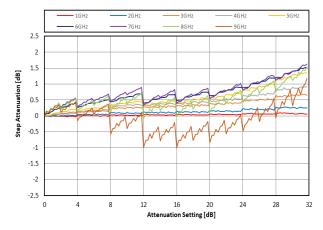
### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### Typical RF Performance Plot - BDA4710V/BDA4710VT EVK - PCB (Optimized Return Loss Application

Typical Performance Data @ 25°C and V<sub>DD</sub> = 3.3V, EVKit RF connector and board losses are de-embedded, unless otherwise noted

Figure 56. 0.25dB Step ATT Error vs Frequency





### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### BDA4710V/BDA4710VT Evaluation board Kit Description

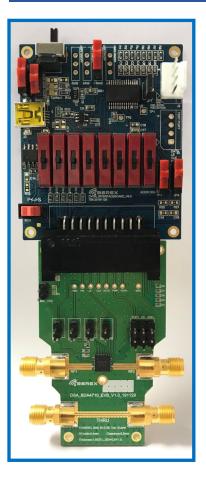


Figure 57. BDA4710V/BDA4710VT EVK

#### **Evaluation board Kit Introduction**

 $\ensuremath{\mathsf{BDA4710V/BDA4710VT}}$  Evaluation Kit is made up of a combination of an RF board and an interface board

The schematic of the BDA4710V/BDA4710VT evaluation RF board is shown in Figure 57. The BDA4710V/BDA4710VT evaluation RF board is constructed of a 4-layer material with a copper thickness of 1oz(0.035mm) on each layer. Every copper layer is separated with a dielectric material. The top dielectric material is 8 mils RO4003. The middle and bottom dielectric materials are FR-4, used for mechanical strength and overall board thickness of approximately 163mm

BDA4710V/BDA4710VT Evaluation INTERFACE board is assembled with a SP3T switches (D0~D6,LE), SP2T mechanical switch (P/S), and several header & switch.

### **Evaluation Board Programming Using USB Interface**

In order to evaluate the BDA4710V/BDA4710VT performance, the Application Software has to be installed on your computer. And The DSA application software GUI supports Latched Parallel and Serial modes. software can be downloaded from BeRex's website

#### Serial Control Mode

- Set the Address Jumper (A0, A1, A2) to HIGH or LOW (Refer to Address Table 9)
- Connect directly the Evaluation INTEFRACE board USB port(J3) to PC
- Set the direction of P<->S Switch to S direction (P/S Logic HIGH)
- Set the D0~D6,LE switch to the middle position.
- Operate the 0~31.75dB attenuation state in GUI and then control the DSA

### **Latched Parallel Control Mode**

- Connect directly the Evaluation INTEFRACE board USB port(J3) to PC
- Set the direction of P<->S Switch to P direction (P/S Logic LOW)
- Set the D0~D6, LE switch to the middle position.
- Operate the 0~31.75dB attenuation state in GUI and then control the DSA

#### **Direct Parallel Control Mode**

- Set the direction of P<->S Switch to P direction (P/S Logic LOW)
- Set LE switch to the LOW Position
- For the setting to attenuation state, D0~D6 switches can be combined in manually program, refer to Table 11.

Please refer to user manual for more detailed operation method of BDA4710V/BDA4710VT



### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### BDA4710V/BDA4710VT Evaluation board Kit Description

Figure 58. Evaluation Board Kit Schematic Diagram

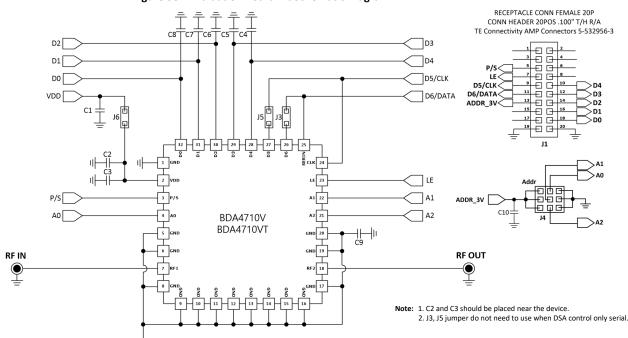


Figure 59. Evaluation Board PCB Layout Information

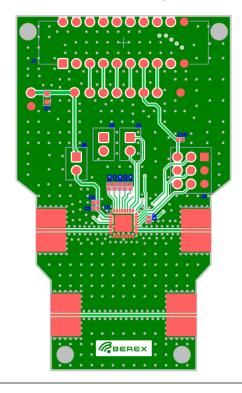
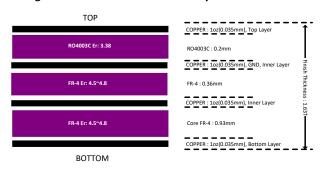


Table 15. Bill of Material - Evaluation Board

No.	Ref Des	Part Qty	Value	Description	Remark
1	C3-C8	6	100pF	CAP, 0402, CHIP Ceramic, ±0.25%	
2	C2,C10	2	100nF	CAP, 0402, CHIP Ceramic, ±0.25%	
3	C9	1	0 ohm	RES, 0402, CHIP, ±5%	
4	U1	1	Chip	DSA, BDA4710V/BDA4710VT QFN5x5 32L	
5	SMA1, SMA2	2	CON	SMA END LAUNCH	
6	J1	1	CON	Receptacle connector 20pin	
7	J2,J3,J5,J6	4	CON	Header 2.54mm 2pin	
8	J4	1	CON	Header array 2.54mm 3pin x 3	
9	C1	1	NC	Not Connected	

Figure 60. Evaluation Board PCB Layer Information



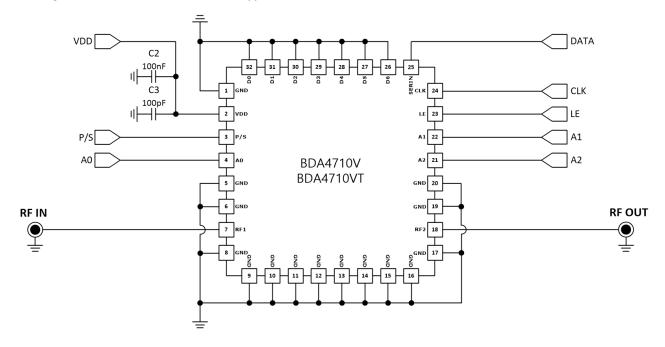
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### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

Figure 61. Recommended Serial mode Application Schematic



Note: 1. C2 and C3 should be placed near the device.

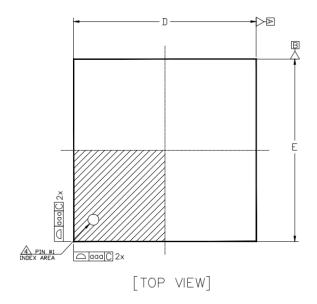
2. Addressable Pin A0,A1,A2 can be set according to the specified address. If the specified address is 000, All addressable pin(A0,A1,A2) should be grounded.

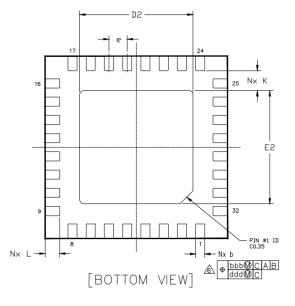


### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

Figure 62. Packing Outline Dimension







### NOTE:

- 1. Dimensioning and tolerancing conform to ASME Y14.5-2009.
- 2. All dimensions are in millimeters.
- 3. N is the total number of terminals.
- 4. The location of the marked terminal #1 identifier is within the hatched area.
- 5. ND and NE refer to the number of terminals on each D and E side respectively.
- 6. Dimension b applies to the metallized terminal and is measured between 0.15mm and 0.30mm from the terminal tip. If the terminal has a radius on the other end of it, dimension b should not be measured in that radius area.
- 7. Coplanarity applies to the terminals and all other bottom surface metallization

	D	imension Table		
Sumbol		Thickness		NOTE
Symbol	MINIMUM	NOMINAL	MAXIMUM	NOTE
Α	0.8	0.9	1	
A1	0	0.02	0.05	
А3		0.203 Ref		
b	0.2	0.25	0.3	6
D		5.0 BSC		
D2	3.05	3.10	3.15	
Е		5.0 BSC		
E2	3.05	3.10	3.15	
е		0.5 BSC		
К	0.2			
L	0.3	0.4	0.5	
aaa		0.05		
bbb		0.1		
ссс		0.1		
ddd		0.05		
eee		0.08		
N		32		3
ND		8		5
NE		8		5

•email: sales@berex.com 23

### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

Figure 63. Recommend Land Pattern

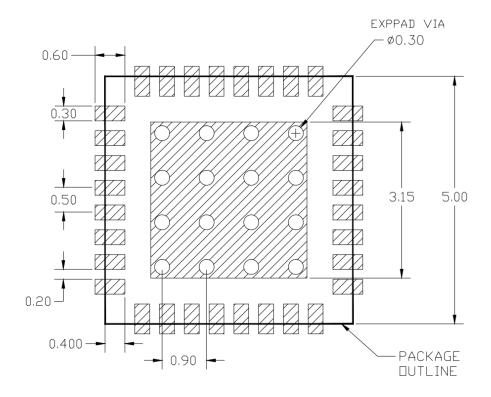


Figure 64. Package Marking





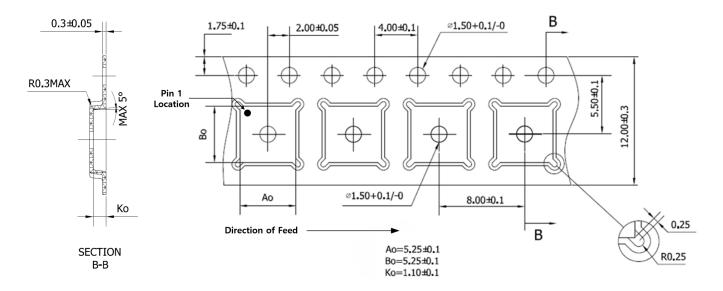
Ma	rking information:
BDA4710V	Device Name : BDA4710V
BDA4710T	Device Name : BDA4710VT
YY	Year
ww	Work Week
XX	LOT Number



### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

Figure 65. Tape & Reel



#### NOTES:

- 1 10 SPROCKET HOLE PITCH CUMULATIVE TOLERANCE ±0.2
- 2 CAMBER IN COMPLANCE WITH EIA 481
- 3 POCKET POSITION RELATIVE TO SPROCKET HOLE MEASURED AS TRUE POSITION OF POCKET, NOT POCKET HOLE

Pack	aging information:
Tape Width	12mm
Reel Size	7inch
Device Cavity Pitch	8mm
Devices Per Reel	1k



### 7-bit Digital Step Attenuator with Addressable Function for Automotive

1MHz - 9000MHz

### Lead plating finish

### 100% Tin Matte finish

(All BeRex products undergoes a 1 hour, 150 degree C, Anneal bake to eliminate thin whisker growth concerns.)

### **ESD / MSL Rating**

ESD Rating: Class 1C Value: ±1000V

Test: Human Body Model (HBM)

Standard: AEC-Q100-002

ESD Rating: Class C3
Value: ±1000V

Test: Charged Device Model (CDM)

Standard: AEC-Q100-011

MSL Rating: Level 1 at +260°C convection reflow
Standard: JEDEC Standard J-STD-020 / JESD22-A113



Proper ESD procedures should be followed when handling this device.

### **RoHS Compliance**

This part is compliant with Restrictions on the use of certain Hazardous Substances in Electrical and Electronic Equipment (RoHS) Directive 2011/65/EU as amended by Directive 2015/863/EU.

This product also is compliant with a concentration of the Substances of Very High Concern (SVHC) candidate list which are contained in a quantity of less than 0.1%(w/w) in each components of a product and/or its packaging placed on the European Community market by the BeRex and Suppliers.

### **NATO CAGE code:**

2   N   9   6   F
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